

# ATV12PU40M3

variable speed drive, Altivar 12, 4kW, 5hp, 3 phases, 200 to 240V, on base plate



## Main

Range of product	Altivar 12
Product or component type	Variable speed drive
Product specific application	Simple machine
Mounting mode	Cabinet mount
Communication port protocol	Modbus
Supply frequency	50/60 Hz +/- 5 %
[Us] rated supply voltage	200...240 V - 15...10 %
Nominal output current	16.7 A
Motor power hp	5 hp
Motor power kW	4 kW
Motor power hp	5 hp
EMC filter	Without EMC filter
IP degree of protection	IP20

## Complementary

Discrete input number	4
Discrete output number	2
Analogue input number	1
Analogue output number	1
Relay output number	1
Physical interface	2-wire RS 485
Connector type	1 RJ45
Continuous output current	16.7 A at 4 kHz
Method of access	Server Modbus serial
Speed drive output frequency	0.5...400 Hz
Speed range	1...20
Sampling duration	20 Ms, tolerance +/- 1 ms for logic input 10 ms for analogue input
Linearity error	+/- 0.3 % of maximum value for analogue input
Frequency resolution	Analog input: converter A/D, 10 bits Display unit: 0.1 Hz
Time constant	20 ms +/- 1 ms for reference change
Transmission rate	9.6 kbit/s 19.2 kbit/s 38.4 kbit/s
Transmission frame	RTU
Number of addresses	1...247
Data format	8 bits, configurable odd, even or no parity
Communication service	Read holding registers (03) 29 words Write single register (06) 29 words Write multiple registers (16) 27 words Read/Write multiple registers (23) 4/4 words Read device identification (43)
Type of polarization	No impedance
4 quadrant operation possible	False

The information provided in this documentation contains general descriptions and/or technical characteristics of the performance of the products contained herein. This documentation is not intended as a substitute for and is not to be used for determining suitability or reliability of these products for specific user applications. It is the duty of any such user or integrator to perform the appropriate and complete risk analysis, evaluation and testing of the products with respect to the relevant specific application or use thereof. Neither Schneider Electric Industries SAS nor any of its affiliates or subsidiaries shall be responsible or liable for misuse of the information contained herein.

Asynchronous motor control profile	Quadratic voltage/frequency ratio Sensorless flux vector control Voltage/frequency ratio (V/f)
Maximum output frequency	4 kHz
Transient overtorque	150...170 % of nominal motor torque depending on drive rating and type of motor
Acceleration and deceleration ramps	S Linear from 0 to 999.9 s U
Motor slip compensation	Preset in factory Adjustable
Switching frequency	2...16 kHz adjustable 4...16 kHz with derating factor
Nominal switching frequency	4 kHz
Braking to standstill	By DC injection
Brake chopper integrated	False
Line current	23.8 A at 100 V (heavy duty) 19.9 A at 120 V (heavy duty)
Maximum input current	19.9 A
Maximum output voltage	240 V
Apparent power	8.3 kVA at 240 V (heavy duty)
Maximum transient current	25.0 A during 60 s (heavy duty) 27.6 A during 2 s (heavy duty)
Network frequency	50...60 Hz
Relative symmetric network frequency tolerance	5 %
Prospective line Isc	5 kA
Base load current at high overload	16.7 A
Power dissipation in W	Natural: 128.0 W
With safety function Safely Limited Speed (SLS)	False
With safety function Safe brake management (SBC/ SBT)	False
With safety function Safe Operating Stop (SOS)	False
With safety function Safe Position (SP)	False
With safety function Safe programmable logic	False
With safety function Safe Speed Monitor (SSM)	False
With safety function Safe Stop 1 (SS1)	False
With sft fct Safe Stop 2 (SS2)	False
With safety function Safe torque off (STO)	False
With safety function Safely Limited Position (SLP)	False
With safety function Safe Direction (SDI)	False
Protection type	Line supply overvoltage Line supply undervoltage Overcurrent between output phases and earth Overheating protection Short-circuit between motor phases Against input phase loss in three-phase Thermal motor protection via the drive by continuous calculation of $I^2t$
Tightening torque	1.2 N.m
Insulation	Electrical between power and control
Quantity per set	Set of 1
Width	140 mm
Height	184 mm
Depth	100.2 mm
Net weight	1.6 kg

## Environment

Operating altitude	<= 1000 m without derating > 1000...3000 m with current derating 1 % per 100 m
Operating position	Vertical +/- 10 degree
Product certifications	NOM[RETURN]CSA[RETURN]C-Tick[RETURN]UL[RETURN]GOST[RETURN]RCM[RETURN]KC
Marking	CE
Standards	UL 508C UL 618000-5-1 IEC 61800-5-1 IEC 61800-3
Assembly style	On base plate
Electromagnetic compatibility	Electrical fast transient/burst immunity test level 4 conforming to IEC 61000-4-4 Electrostatic discharge immunity test level 3 conforming to IEC 61000-4-2 Immunity to conducted disturbances level 3 conforming to IEC 61000-4-6 Radiated radio-frequency electromagnetic field immunity test level 3 conforming to IEC 61000-4-3 Surge immunity test level 3 conforming to IEC 61000-4-5 Voltage dips and interruptions immunity test conforming to IEC 61000-4-11
Environmental class (during operation)	Class 3C3 according to IEC 60721-3-3 Class 3S2 according to IEC 60721-3-3
Maximum acceleration under shock impact (during operation)	150 m/s <sup>2</sup> at 11 ms
Maximum acceleration under vibrational stress (during operation)	10 m/s <sup>2</sup> at 13...200 Hz
Maximum deflection under vibratory load (during operation)	1.5 mm at 2...13 Hz
Overvoltage category	Class III
Regulation loop	Adjustable PID regulator
Electromagnetic emission	Radiated emissions environment 1 category C2 conforming to IEC 61800-3 2...16 kHz shielded motor cable Conducted emissions conforming to IEC 61800-3
Vibration resistance	1 gn (f = 13...200 Hz) conforming to IEC 60068-2-6 1.5 mm peak to peak (f = 3...13 Hz) - drive unmounted on symmetrical DIN rail - conforming to IEC 60068-2-6
Shock resistance	15 gn conforming to IEC 60068-2-27 for 11 ms
Relative humidity	5...95 % without condensation conforming to IEC 60068-2-3 5...95 % without dripping water conforming to IEC 60068-2-3
Noise level	0 dB
Pollution degree	2
Ambient air transport temperature	-25...70 °C
Ambient air temperature for operation	-10...40 °C without derating 40...60 °C with current derating 2.2 % per °C
Ambient air temperature for storage	-25...70 °C

## Packing Units

Unit Type of Package 1	PCE
Number of Units in Package 1	1
Package 1 Height	27.000 cm
Package 1 Width	19.000 cm
Package 1 Length	24.500 cm
Package 1 Weight	2.202 kg
Unit Type of Package 2	P06
Number of Units in Package 2	12
Package 2 Height	75.000 cm
Package 2 Width	60.000 cm
Package 2 Length	80.000 cm
Package 2 Weight	39.424 kg

## Offer Sustainability

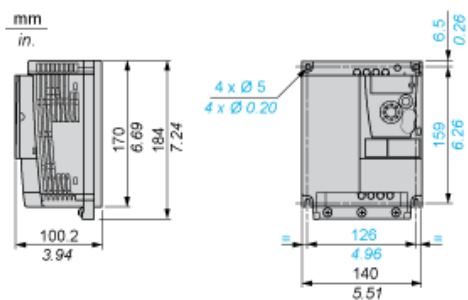
REACH Regulation	 <a href="#">REACH Declaration</a>
EU RoHS Directive	Pro-active compliance (Product out of EU RoHS legal scope)
Mercury free	Yes
China RoHS Regulation	 <a href="#">China RoHS Declaration</a>
RoHS exemption information	 Yes
WEEE	The product must be disposed on European Union markets following specific waste collection and never end up in rubbish bins

## Contractual warranty

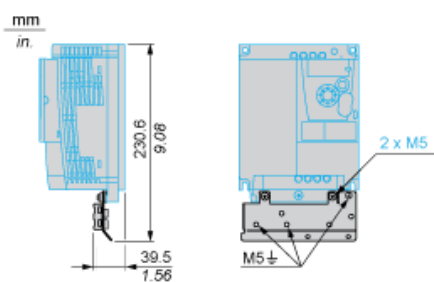
Warranty	18 months
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## Dimensions

### Drive without EMC Conformity Kit

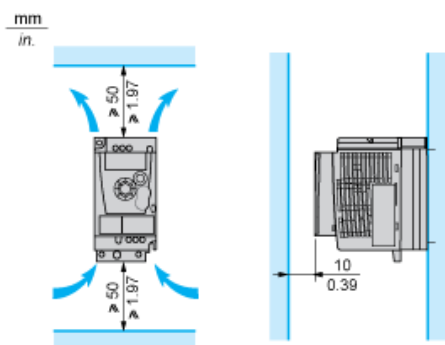


### Drive with EMC Conformity Kit

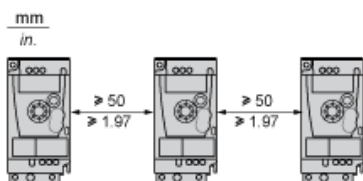


## Mounting Recommendations

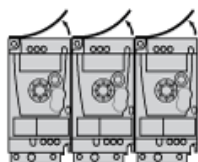
### Clearance for Vertical Mounting



### Mounting Type A

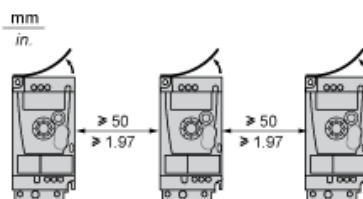


### Mounting Type B



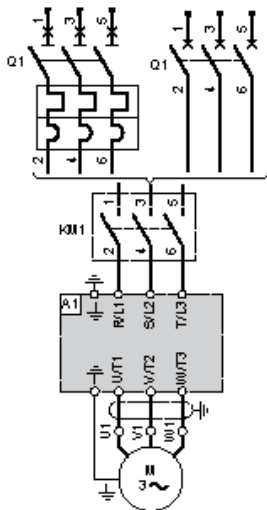
Remove the protective cover from the top of the drive.

### Mounting Type C



Remove the protective cover from the top of the drive.

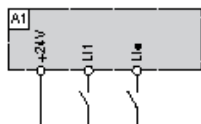
### Three-Phase Power Supply Wiring Diagram



- A1 Drive  
KM1 Contactor (only if a control circuit is needed)  
Q1 Circuit breaker

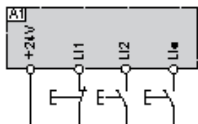
### Recommended Schemes

#### 2-Wire Control for Logic I/O with Internal Power Supply



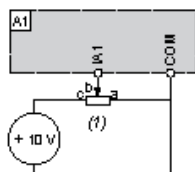
- L1 : Forward  
L1• : Reverse  
A1 : Drive

#### 3-Wire Control for Logic I/O with Internal Power Supply



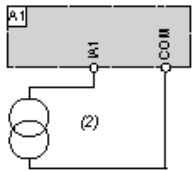
- L1 : Stop  
L2 : Forward  
L1• : Reverse  
A1 : Drive

#### Analog Input Configured for Voltage with Internal Power Supply



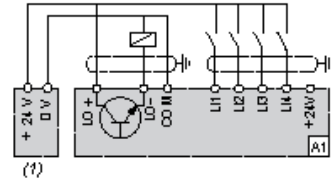
- (1) 2.2 kΩ...10 kΩ reference potentiometer  
A1 : Drive

## Analog Input Configured for Current with Internal Power Supply



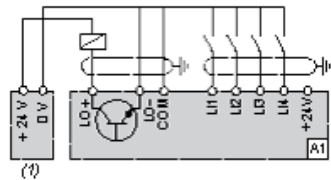
(2) 0-20 mA 4-20 mA supply  
A1 : Drive

## Connected as Positive Logic (Source) with External 24 vdc Supply



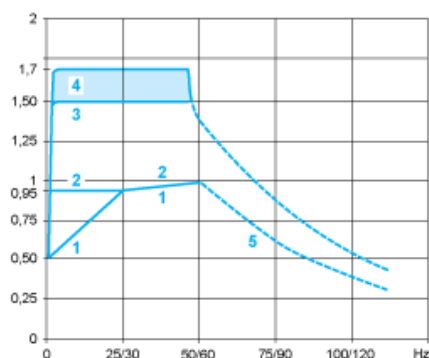
(1) 24 vdc supply  
A1 : Drive

## Connected as Negative Logic (Sink) with External 24 vdc supply



(1) 24 vdc supply  
A1 : Drive

## Torque Curves



- 1 : Self-cooled motor: continuous useful torque (1)
- 2 : Force-cooled motor: continuous useful torque
- 3 : Transient overtorque for 60 s
- 4 : Transient overtorque for 2 s
- 5 : Torque in overspeed at constant power (2)

(1) For power ratings  $\leq 250$  W, derating is 20% instead of 50% at very low frequencies.

(2) The nominal motor frequency and the maximum output frequency can be adjusted from 0.5 to 400 Hz. The mechanical overspeed capability of the selected motor must be checked with the manufacturer.